

## **IN THE CLAIMS**

*This listing of claims will replace all prior versions and listings of claims in the application.*

### **Listing of the Claims:**

1. (Original) A target travel direction detecting method comprising: an image acquiring step of acquiring an image including a target picked up at predetermined time intervals;  
an extracted image creating step of creating an image including an arbitrary component extracted from the image;  
a target position detecting step of causing a matrix template to scan the extracted image at time  $t$  to detect the position of the target;  
a pixel value storing step of storing each pixel value of the extracted image at time  $t$  into the template;  
a value-matching pixel detecting step of causing a template storing the pixel value to scan the extracted image at time  $t+1$  to detect the position of a pixel whose value matches a pixel value of the template; and  
a travel-direction-extracted image creating step of plotting a pixel value set to accordance with the travel direction of the target at the same coordinate position as the pixel position detected in the value-matching pixel detecting step to create a travel-direction-extracted image.

2. (Original) A target travel direction detecting method comprising: an image acquiring step of acquiring an image including a target picked up at predetermined time intervals;  
an extracted image creating step of creating respective images including arbitrary components extracted from the image;  
a target position detecting step of respectively causing a matrix template to scan each of the extracted images at time  $t$  to respectively detect the position of the target;  
a pixel value storing step of storing each pixel value of each of the extracted images at time  $t$  into each of the templates;

a value-matching pixel detecting step of causing each template storing the pixel value to scan each of the extracted images at time  $t+1$  to respectively detect the position of a pixel whose value matches each pixel value of each of the templates; and

a travel-direction-extracted image creating step of plotting a pixel value set to accordance with the travel direction of the target at the same coordinate position as each of the pixel positions detected in the value-matching pixel detecting step to respectively create a plurality of travel-direction-extracted images and obtain, per pixel, the mean value of the plurality of travel-direction-extracted images in order to create a complex travel-direction-extracted image.

3. (Currently Amended) The target travel direction detecting method according to claim 1 or 2, wherein

the travel-direction-extracted image creating step includes a speed calculating step of obtaining a speed of the target based on the distance between the position of a first center of gravity as a center of gravity of the target in a first travel-direction-extracted image created based on an image picked up at time  $t$  and an image picked up at time  $t+1$ , and the position of a second center of gravity as a center of gravity of the target in a second travel-direction-extracted image created based on an image picked up at time  $t+1$  and an image picked up at time  $t+2$ .

4. (Currently Amended) The target travel direction detecting method according to ~~any one of claims 1 through 3~~ claim 1, wherein

the extracted image creating step selects and extracts a lightness component, a hue component and a chroma component from a color image.

5. (Currently Amended) The target travel direction detecting method according to ~~any one of claims 1 through 4~~ claim 1, comprising

a space-time image creating step of creating a space-time image where images in a predetermined area extracted from each of the travel-direction-extracted images created in the travel-direction-extracted image creating step are arranged in chronological order.

6. (New) The target travel direction detecting method according to claim 2, wherein the travel-direction-extracted image creating step includes a speed calculating step of obtaining a speed of the target based on the distance between the position of a first center of gravity as a center of gravity of the target in a first travel-direction-extracted image created based on an image picked up at time  $t$  and an image picked up at time  $t+1$ , and the position of a second center of gravity as a center of gravity of the target in a second travel-direction-extracted image created based on an image picked up at time  $t+1$  and an image picked up at time  $t+2$ .

7. (New) The target travel direction detecting method according to claim 2, wherein the extracted image creating step selects and extracts a lightness component, a hue component and a chroma component from a color image.

8. (New) The target travel direction detecting method according to claim 3, wherein the extracted image creating step selects and extracts a lightness component, a hue component and a chroma component from a color image.

9. (New) The target travel direction detecting method according to claim 2, comprising a space-time image creating step of creating a space-time image where images in a predetermined area extracted from each of the travel-direction-extracted images created in the travel-direction-extracted image creating step are arranged in chronological order.

10. (New) The target travel direction detecting method according to claim 3, comprising a space-time image creating step of creating a space-time image where images in a predetermined area extracted from each of the travel-direction-extracted images created in the travel-direction-extracted image creating step are arranged in chronological order.

11. (New) The target travel direction detecting method according to any claim 4, comprising

a space-time image creating step of creating a space-time image where images in a predetermined area extracted from each of the travel-direction-extracted images created in the travel-direction-extracted image creating step are arranged in chronological order.